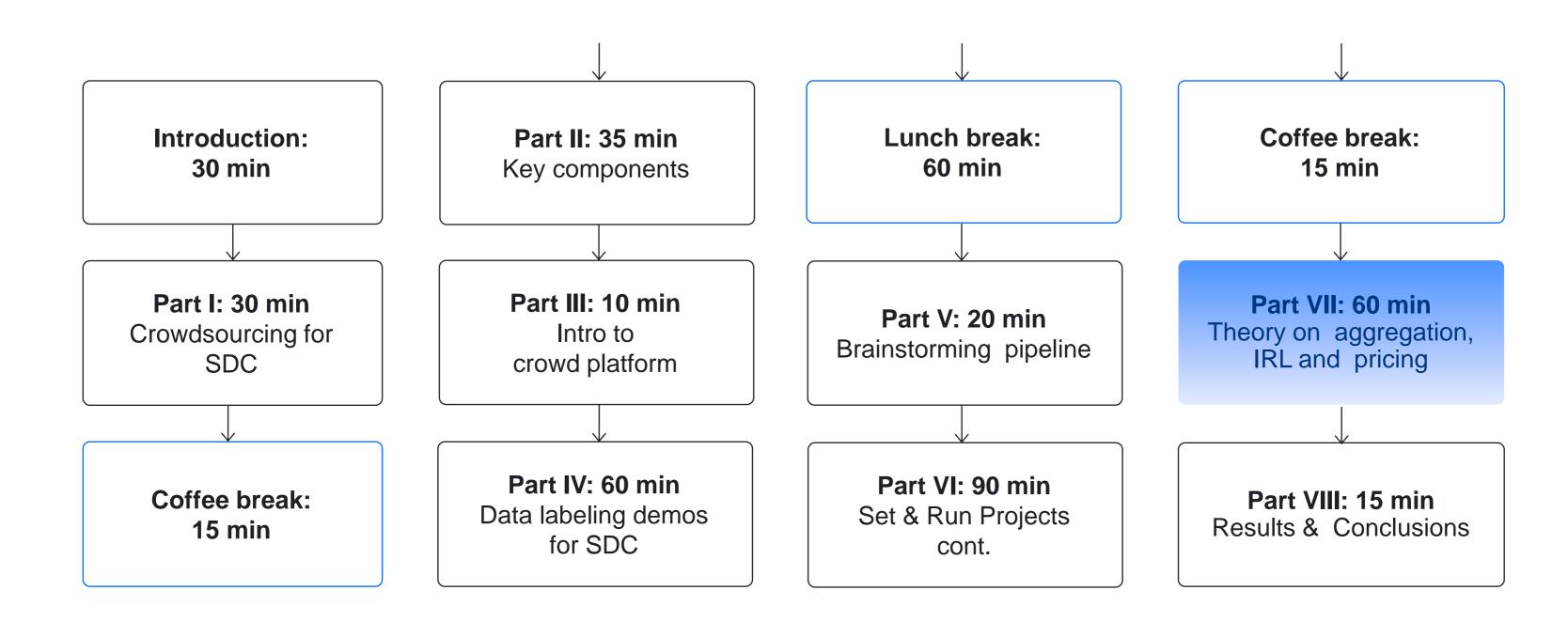
Part VII

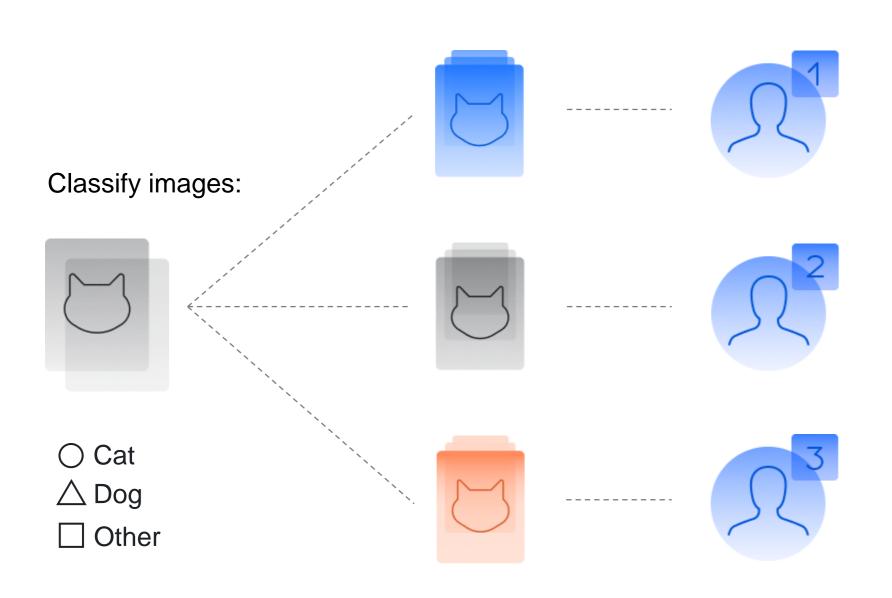
# Theory on Aggregation

Alexey Drutsa, Head of Efficiency and Growth Division, Toloka

#### Tutorial schedule

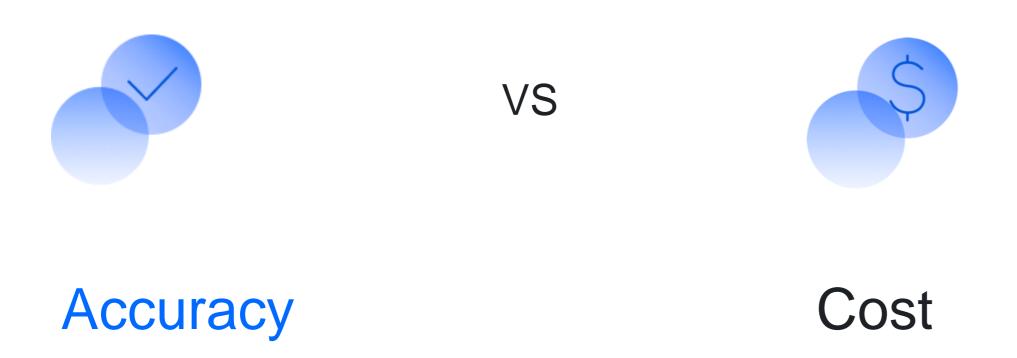


#### Labeling data with crowdsourcing



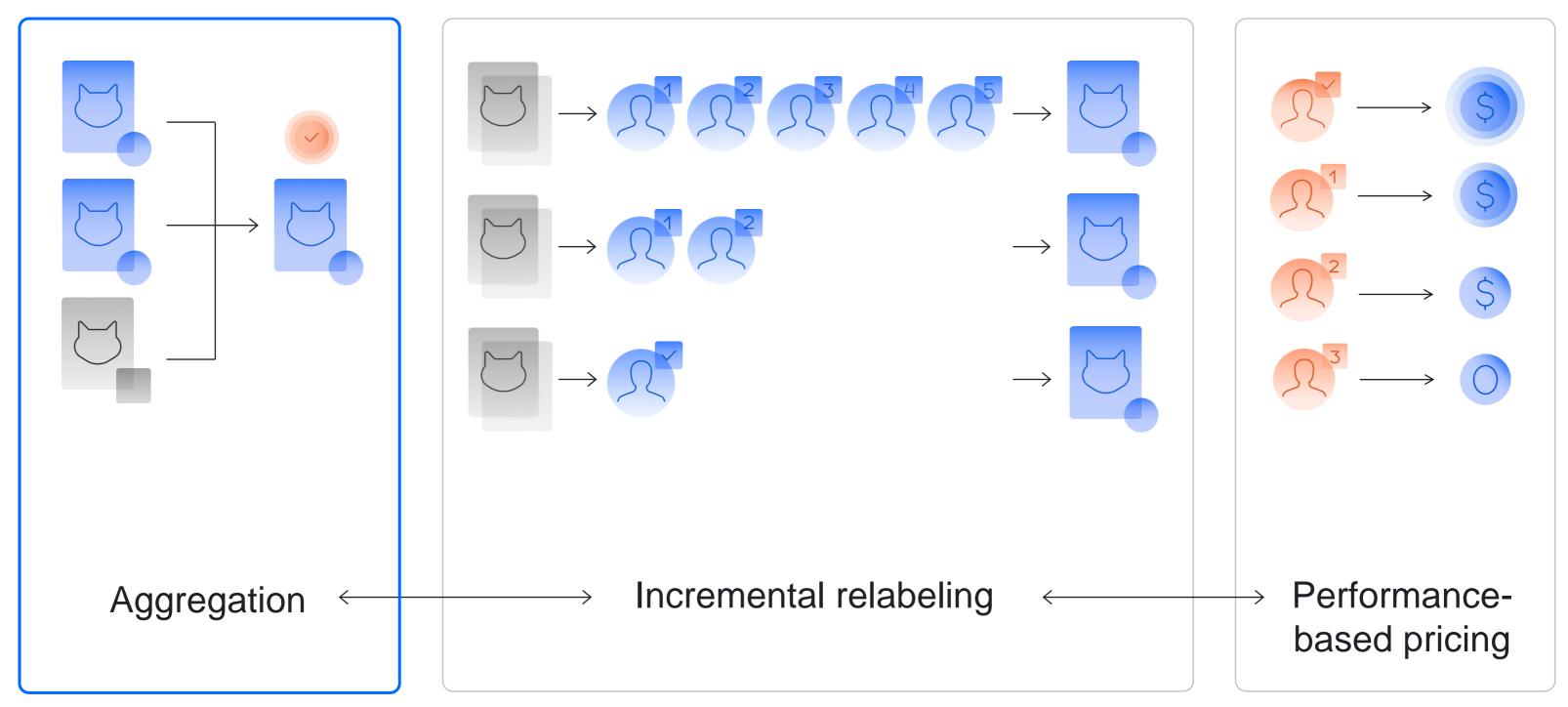
- ► How to choose a reliable label?
- ► How many labels per object?
- ► How much to pay for labels?
- **...**

#### Evaluation of labeling approaches



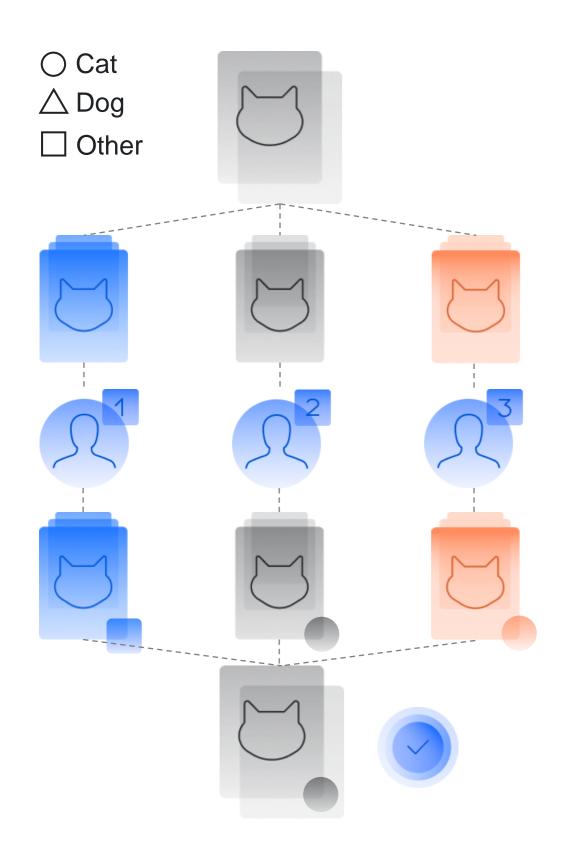
- ► Labels with a maximal level of accuracy for a given budget
- ► Labels of a chosen accuracy level for a minimal budget

#### Key components of labeling with crowds



## Aggregation

#### Labeling data with crowds



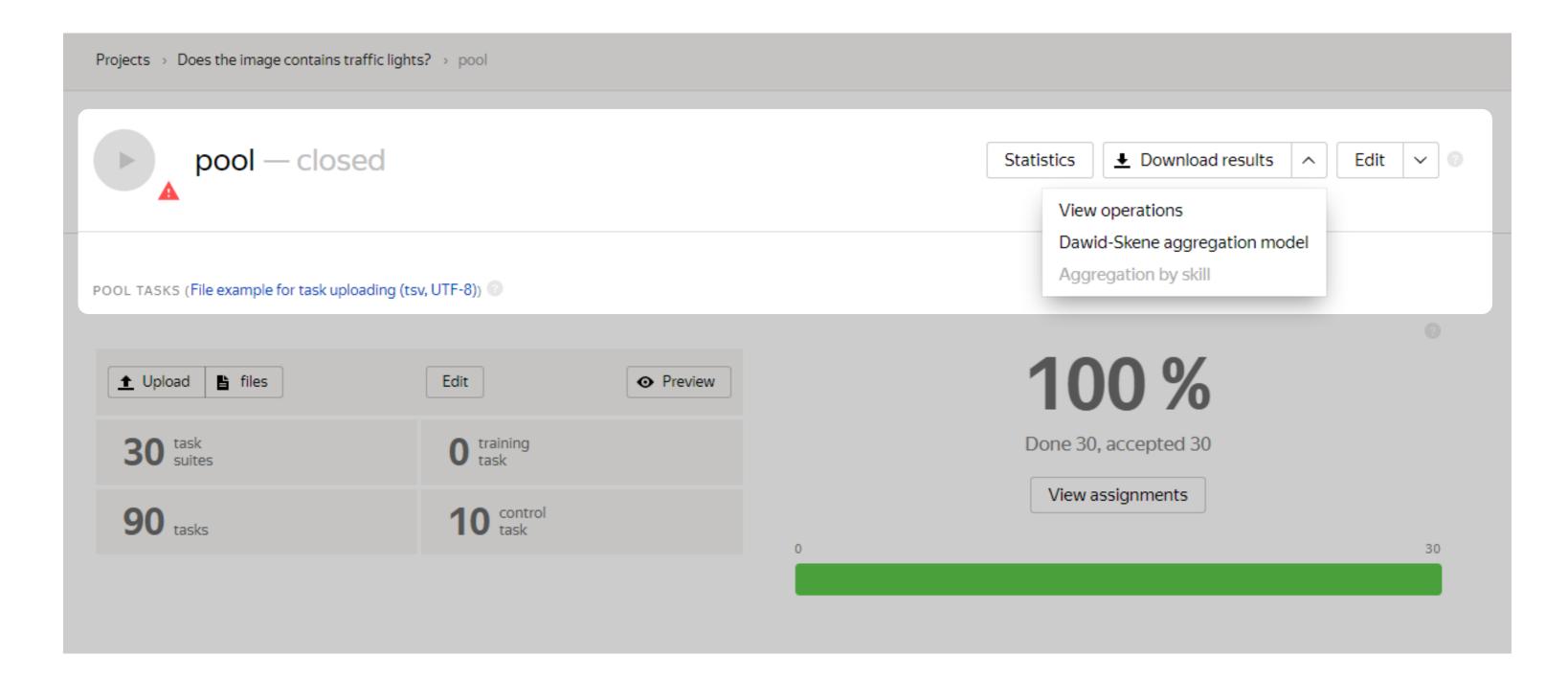
Classify images

Upload multiple copies of each object to label

Performers assign noisy labels to objects

Aggregate multiple labels for each object into a more reliable one

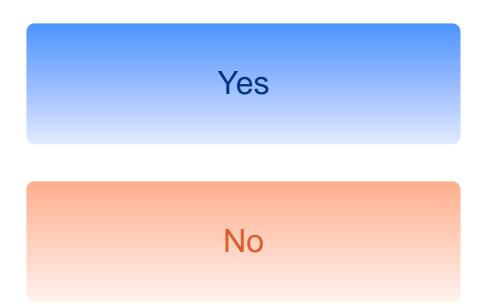
#### Process results



### Multiclass labels

#### Project 1: Filter images

Are there traffic lights in the picture?





#### Notation

- Categories k∈{1,...,K}. E.g.:
- ▶ Objects j∈{1,...,J}. E.g.:

- ► Performers: w∈{1,...,W}. E.g.:
  - W\_j⊆{1,...,W} performers labeled object j





















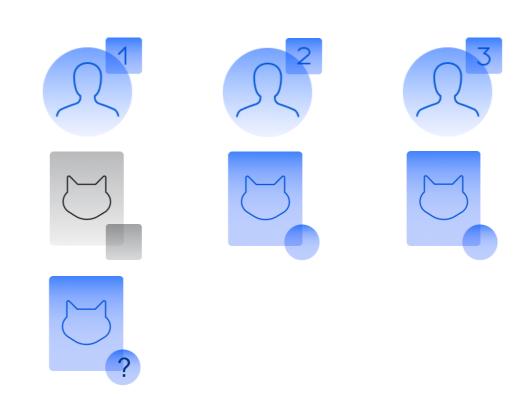


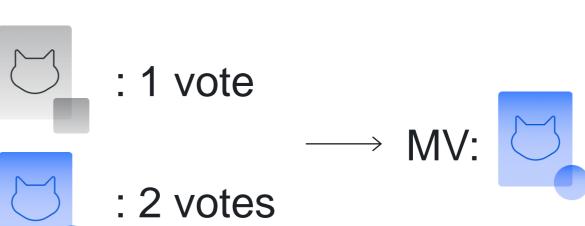
#### The simplest aggregation: Majority Vote (MV)

- ► The problem of aggregation:
  - Observe noisy labels

$$y = \{y_j^w | j = 1, ..., J \text{ and } w = 1, ..., W\}$$

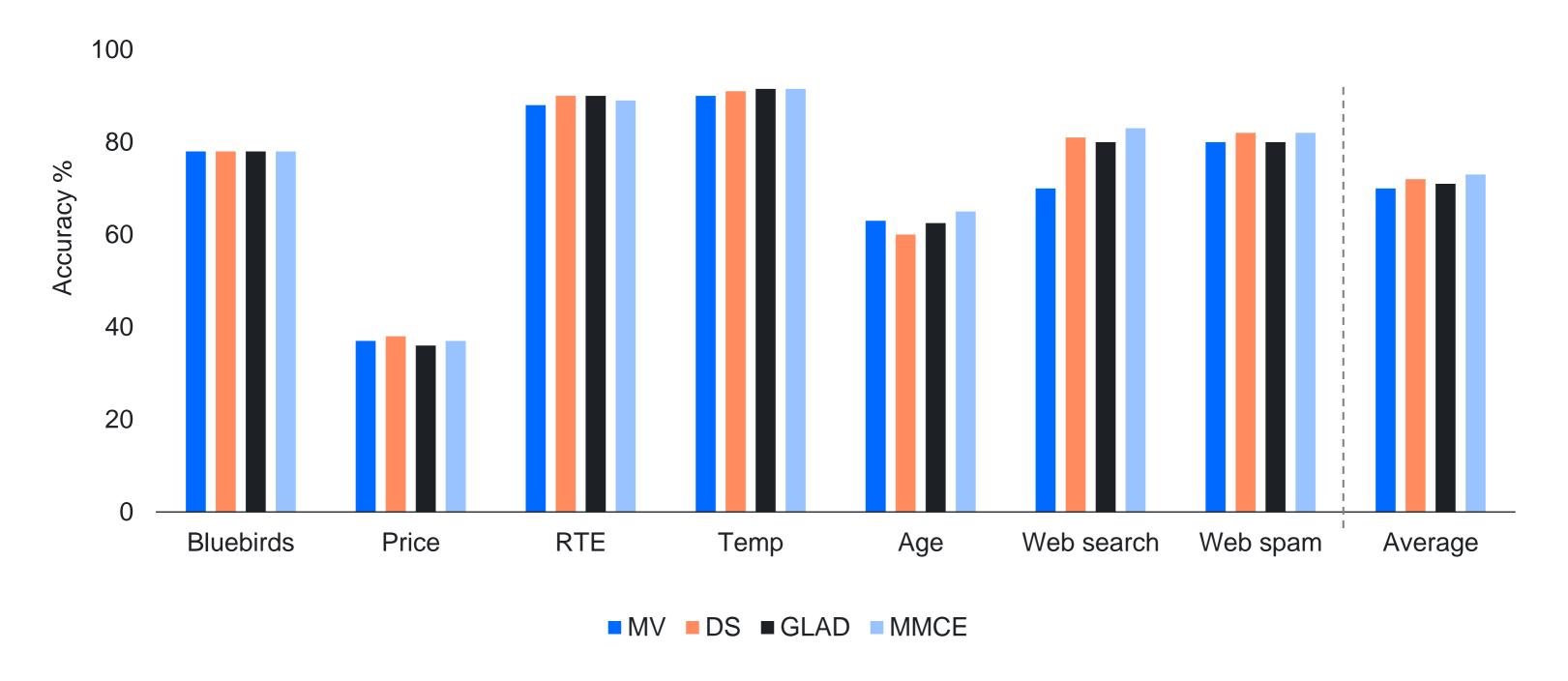
- Recover true labels  $z = \{z_j | j = 1, ..., J\}$
- A straightforward solution:





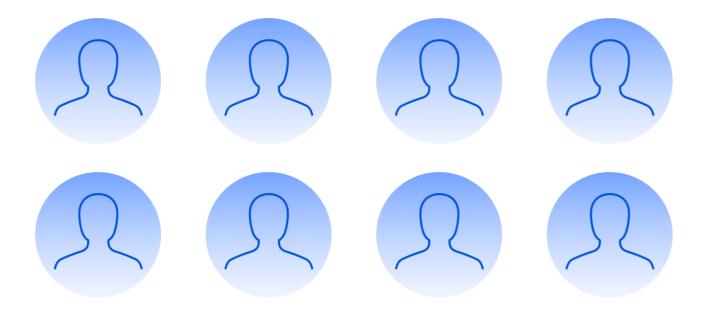
$$\hat{\mathbf{z}}_{j}^{MV} = \arg\max_{\mathbf{v}=1,\dots,K} \sum_{\mathbf{w}\in\mathbf{W}_{j}} \delta(\mathbf{y} = \mathbf{y}_{j}^{\mathbf{w}}), \text{ where } \delta(\mathbf{A}) = 1 \text{ if A is true and 0 otherwise}$$

#### Performance of MV vs other methods

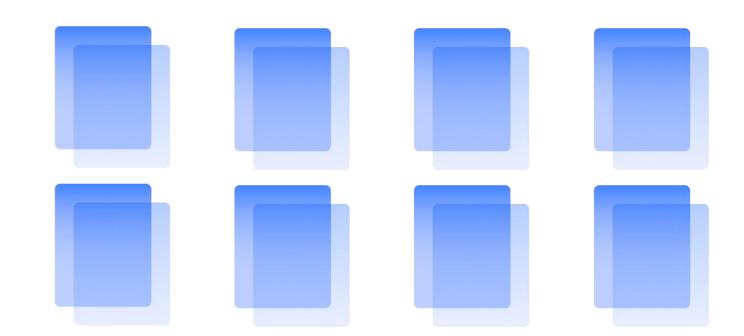


#### Properties of MV

All performers are treated similarly

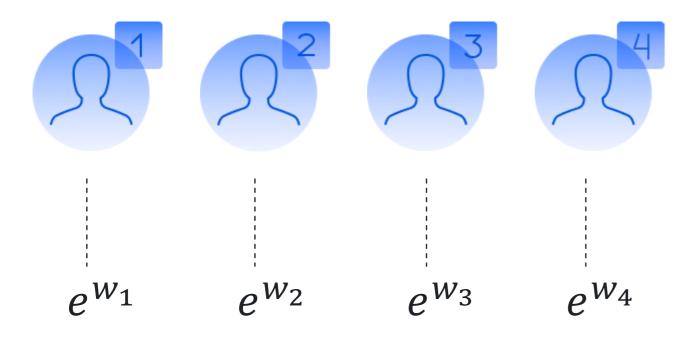


All objects are treated similarly

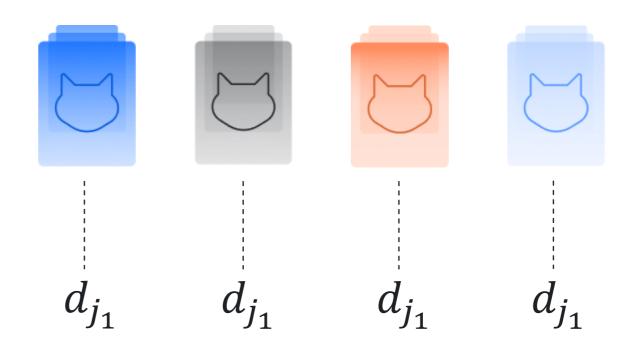


#### Advanced aggregation: performers and objects

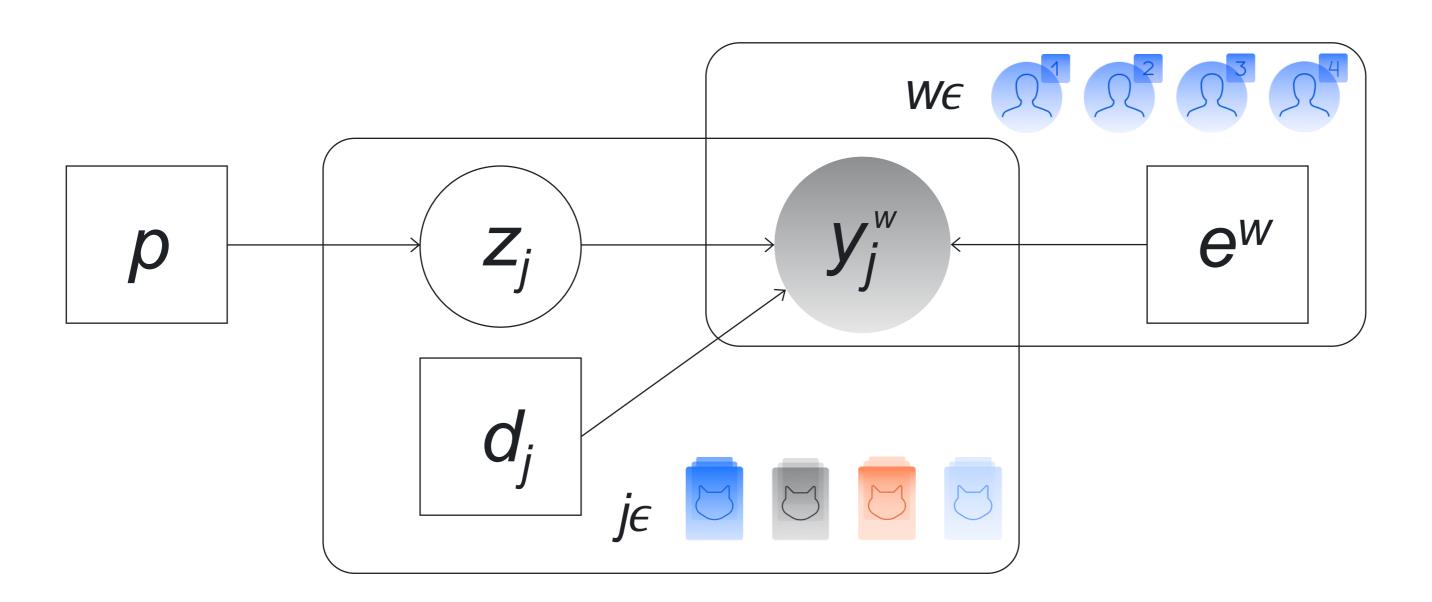
Parameterize expertise of performers by  $e^{w}$ 



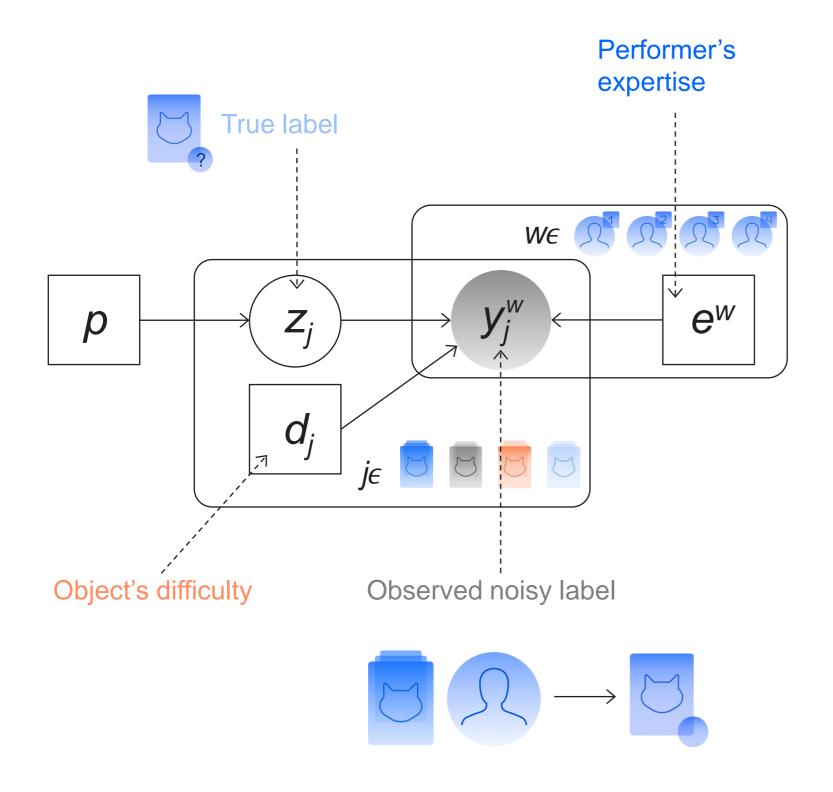
Parameterize difficulty of objects by  $d_i$ 



#### Advanced aggregation: latent label models

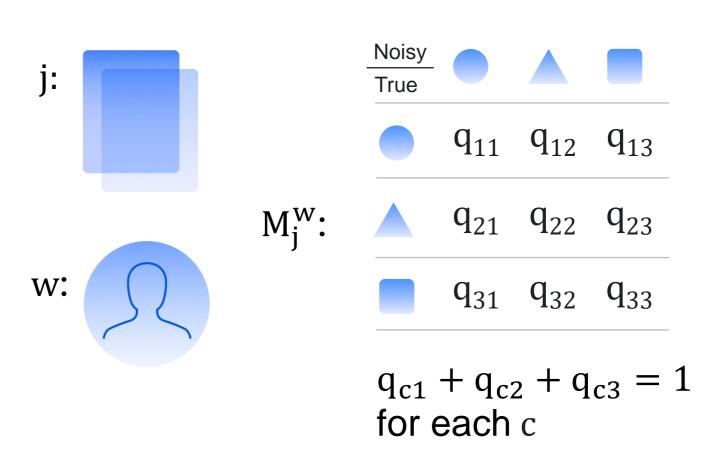


#### Latent label models: noisy label model

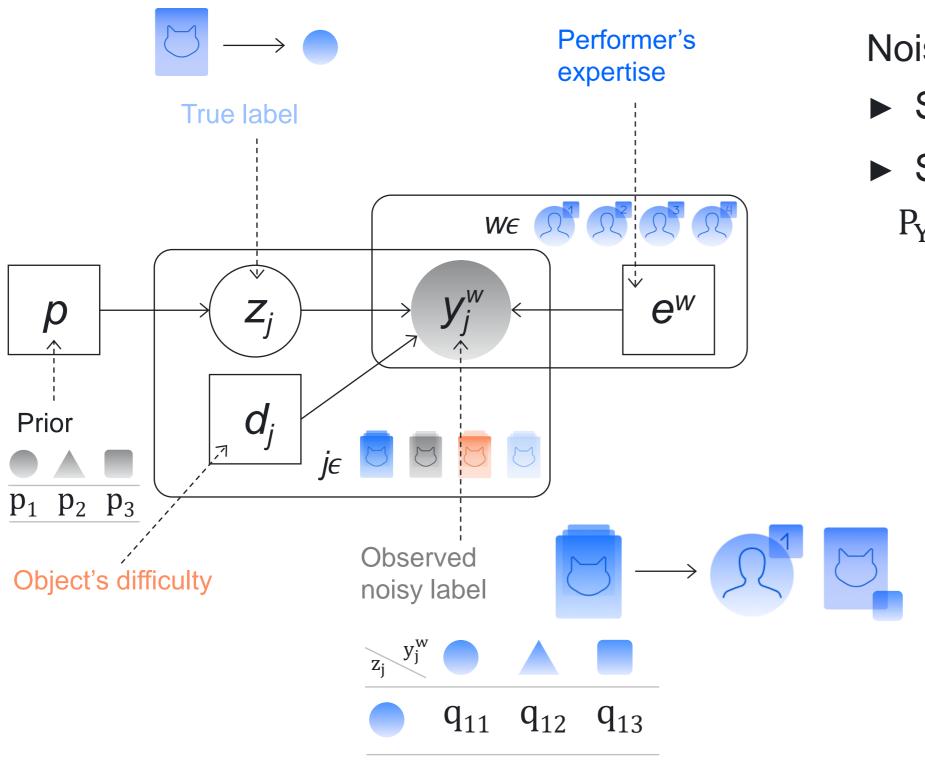


A noisy label model  $M_j^w = M(e^w, d_j)$  is a matrix of size  $K \times K$  with elements

$$M_j^w[c,k] = Pr(Y_j^w = k | Z_j = c)$$



#### Latent label models: generative process



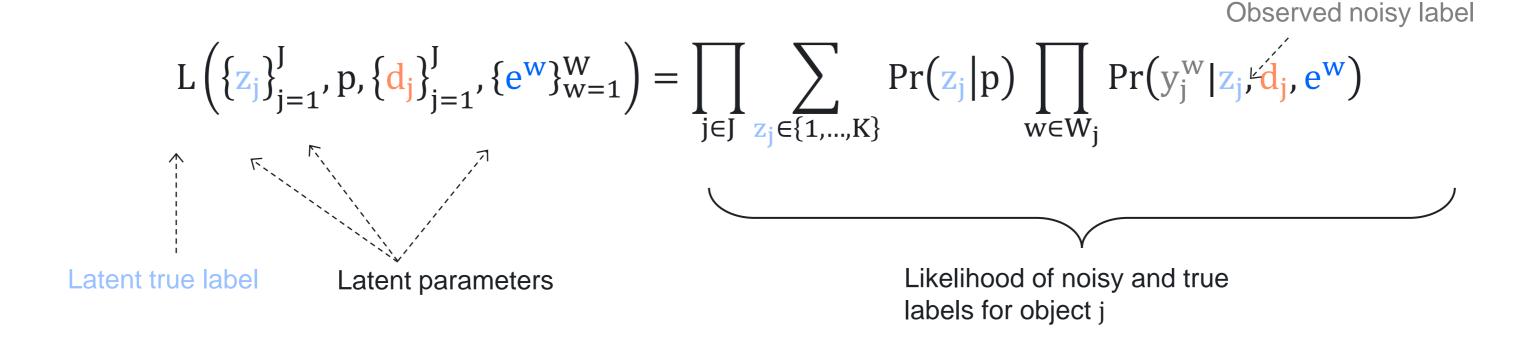
Noisy labels generation:

- ightharpoonup Sample  $z_i$  from a distribution  $P_Z(p)$
- ► Sample  $y_j^w$  from a distribution  $P_Y(M_i^w[z_j,\cdot])$

In multiclassification, a standard choice for  $P_Z(\cdot)$  and  $P_Y(\cdot)$  is a Multinomial distribution  $Mult(\cdot)$ 

#### Latent label models: parameters optimization

- ightharpoonup Assumption:  $y_j^W$  is cond. independent of everything else given  $z_j$ ,  $d_j$ ,  $e^W$
- ► The likelihood of y and z under the latent label model:



► Estimate parameters and true labels by maximizing L(...)

#### Latent label models: EM algorithm

► Maximization of the expectation of log-likelihood (LL), a lower bound on LL of y and z

$$\mathbb{E}_{\mathbf{z}}\log \Pr(\mathbf{y}, \mathbf{z}) = \sum_{\mathbf{j} \in \mathbf{J}} \sum_{\mathbf{z}_{\mathbf{j}} \in \{1, \dots, K\}} \Pr(\mathbf{z}_{\mathbf{j}} | \mathbf{p}) \log \prod_{\mathbf{w} \in \mathbf{W}_{\mathbf{j}}} \Pr(\mathbf{z}_{\mathbf{j}} | \mathbf{p}) \Pr(\mathbf{y}_{\mathbf{j}}^{\mathbf{w}} | \mathbf{z}_{\mathbf{j}}, \mathbf{d}_{\mathbf{j}}, \mathbf{e}^{\mathbf{w}})$$

► E-step: Use Bayes' theorem for posterior distribution of  $\hat{z}$  given p, d, e:

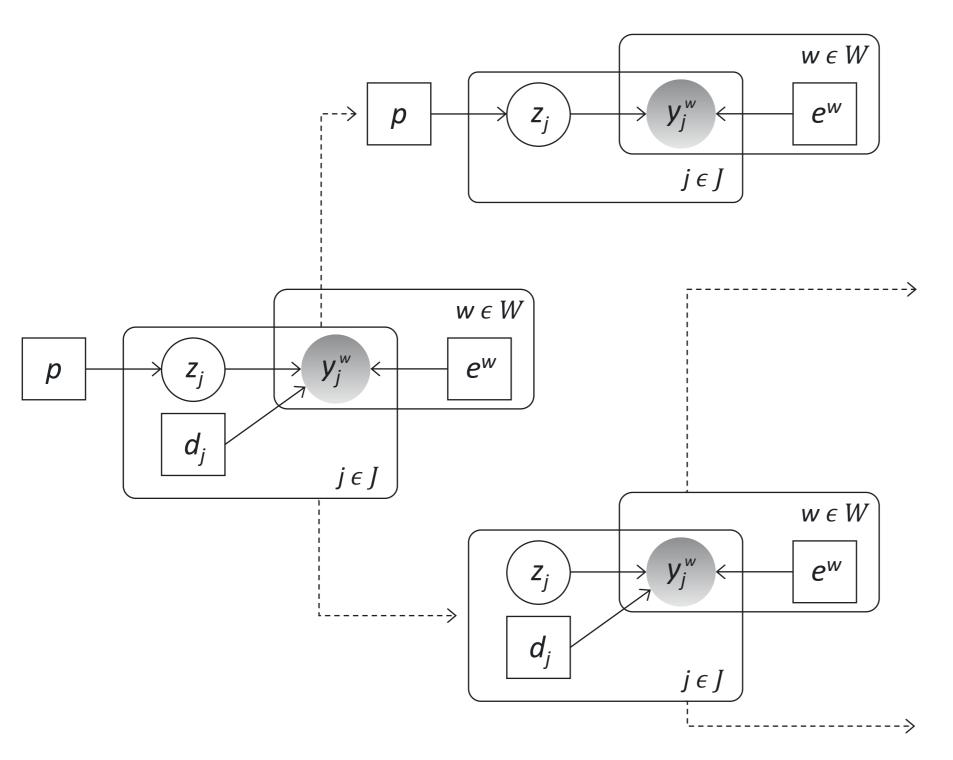
$$\hat{z}_j[c] = \Pr(Z_j = c|y, p, d, e) \propto \Pr(Z_j = c|p) \prod_{w \in W_i} \Pr(y_j^w|Z_j = c, d_j, e^w)$$

▶ M-step: Maximize the expectation of LL with respect to the posterior distribution of  $\hat{z}$ :

$$(p, d, e) = \operatorname{argmax} \mathbb{E}_{\hat{z}} \log \Pr(z_j|p) \prod_{w \in W_i} \Pr(y_j^w|z_j, d_j, e^w)$$

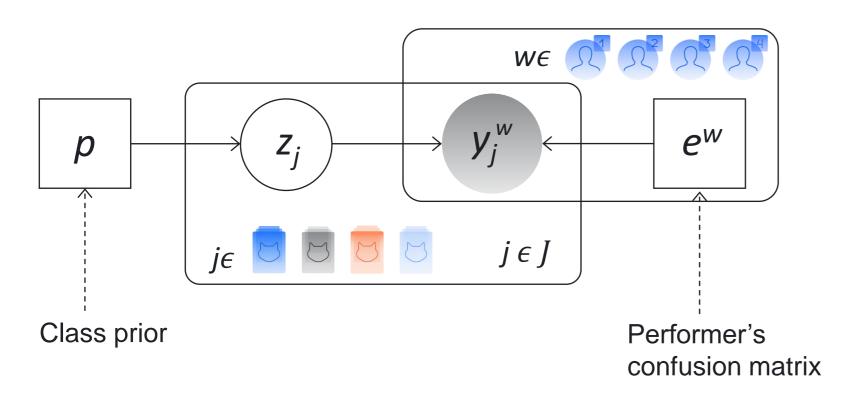
- Analytical solutions
- Gradient descent

#### Latent label model (LLM): special cases



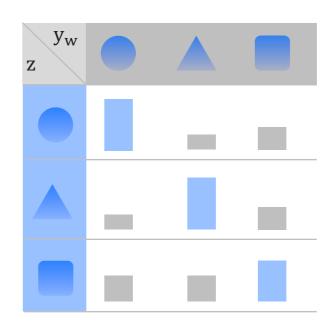
- ▶ Dawid and Skene model (DS):
  - Categories are different
  - Objects are similar
  - Performers are different
- ► Generative model of labels, abilities, and difficulties (GLAD):
  - Categories are similar
  - Objects are different
  - Performers are different
- Minimax conditional entropy model (MMCE):
  - Categories are different
  - Objects are different
  - Performers are different

#### Dawid and Skene model (DS)



#### LLM with parameters:

- ► p vector of length K: p[i] = Pr(Z = c)
- $e^w$  matrix of size  $K \times K$ :  $e^w[c, k] = Pr(Y^w = k|Z = c)$



#### DS: parameters optimization

► E-step:

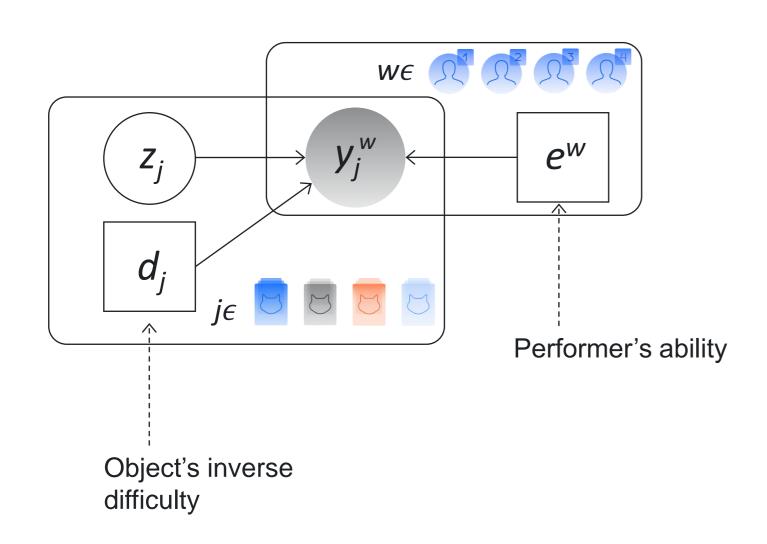
$$\widehat{z_j}[c] = \frac{p[c] \prod_{w \in W_j} e^w[c, y_j^w]}{\sum_k p[k] \prod_{w \in W_j} e^w[k, y_j^w]}, \qquad c = 1, ..., K$$

► M-step: Analytical solution

$$\mathbf{e^{w}}[c,k] = \frac{\sum_{j \in J} \widehat{z_{j}}[c]\delta(y_{j}^{w} = k)}{\sum_{q=1}^{K} \sum_{j \in J} \widehat{z_{j}}[c]\delta(y_{j}^{w} = q)}, \quad k, c = 1, ..., K$$

$$p[c] = \frac{\sum_{j \in J} \widehat{z_j}[c]}{J}, \qquad c = 1, ..., K$$

## Generative model of Labels, Abilities, and Difficulties (GLAD)



#### LLM with parameters:

- ▶ Scalar  $d_i \in (0, \infty)$
- ▶ Scalar  $e^w \in (-\infty, \infty)$
- ► Model:

$$Pr(Y_j^W = k | \mathbf{Z}_j = c) = \begin{cases} a(w, j), & c = k \\ \frac{1 - a(w, j)}{K - 1}, c \neq k \end{cases}$$

where 
$$a(w,j) = \frac{1}{1 + \exp(-e^{w}d_{j})}$$

#### GLAD: parameters optimization

► Let  $a(w,j) = \frac{1}{1 + \exp(-e^w d_j)}$  and  $P(z_j)$  be a predefined prior (e.g.,  $P(z_j) = \frac{1}{K}$ )

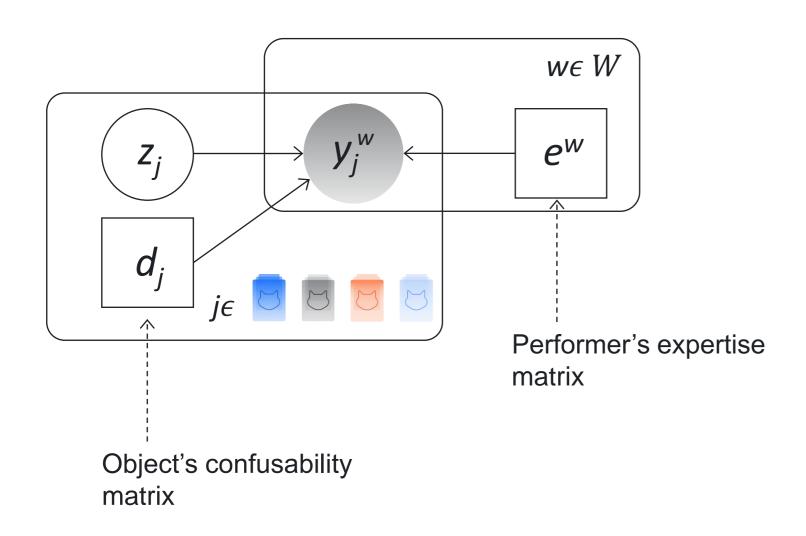
► E-step:

$$\widehat{z_j}\left[c\right] \propto P\left(Z_j = c\right) \prod_{w \in W_j} a(w, j)^{\delta\left(y_j^W = c\right)} \left(\frac{1 - a(w, j)}{K - 1}\right)^{\delta\left(y_j^W \neq c\right)}, \ c = 1, \dots, K$$

▶ M-step: estimate (d, e) for given  $\hat{z}$  using gradient descent

$$(d^{t}, e^{t}) = \operatorname{argmax} \sum_{j \in J} \left[ \mathbb{E}_{\widehat{z}_{j}} \log P(z_{j}) + \sum_{w \in W_{j}} \mathbb{E}_{\widehat{z}_{j}} \log Pr(y_{j}^{w}|z_{j}) \right]$$

#### MiniMax Conditional Entropy model (MMCE)



► Find parameters that minimize the maximum conditional entropy of observed labels:

$$\begin{aligned} \text{min}_{Q} \text{max}_{P} - \sum_{\substack{j \in J \\ c \in \{1, \dots, K\}}} Q \big( Z_{j} = c \big) \sum_{\substack{w \in W \\ k \in \{1, \dots, K\}}} P \big( Y_{j}^{\text{w}} = k | Z_{j} = c \big) \text{log } P \big( Y_{j}^{\text{w}} = k | Z_{j} = c \big) \end{aligned}$$

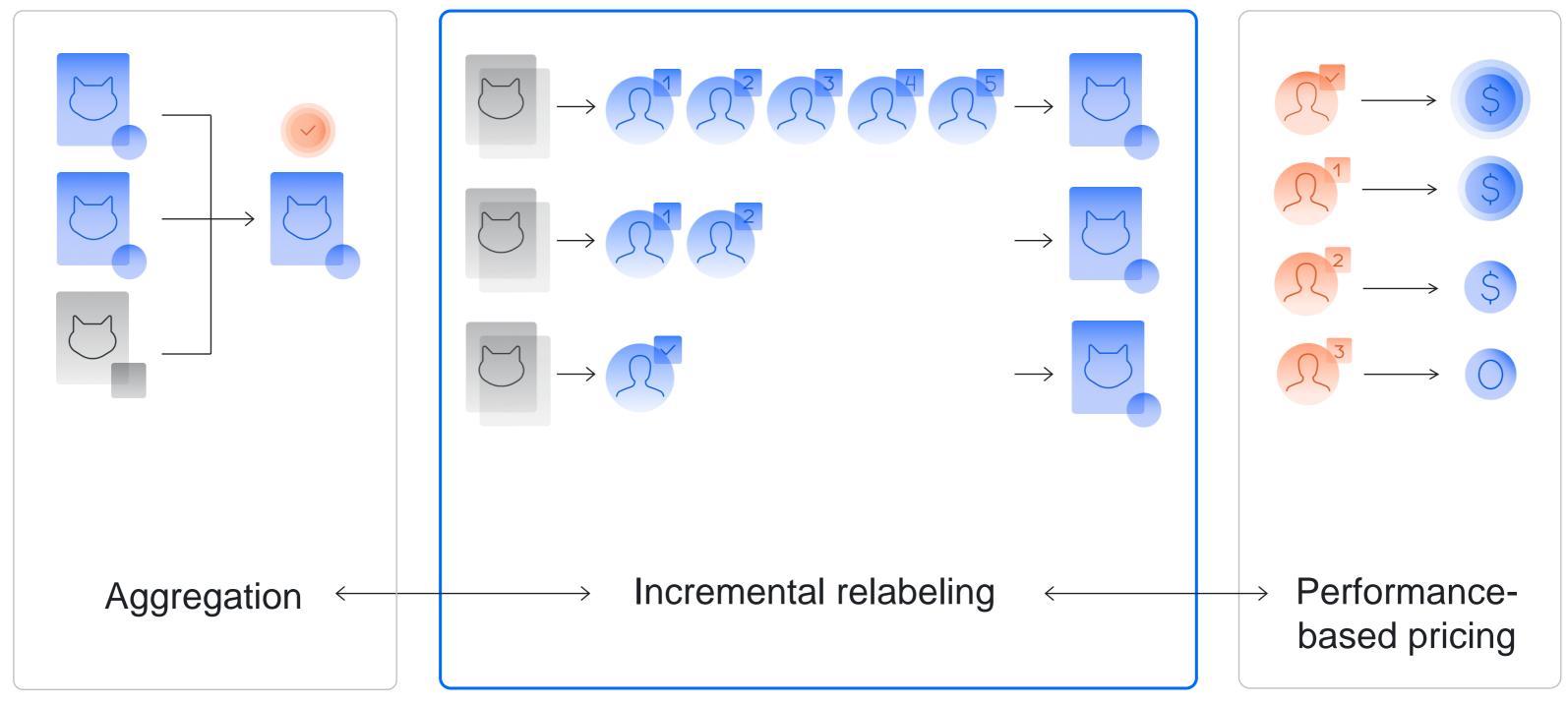
- ► LLM with parameters:
  - d<sub>i</sub> matrix of size K × K
  - e<sup>w</sup> matrix of size K × K
  - Noisy label model:

$$Pr(Y_j^W = k|Z_j = c) = exp(d_j[c, k] + e^W[c, k])$$

#### Summary of aggregation methods

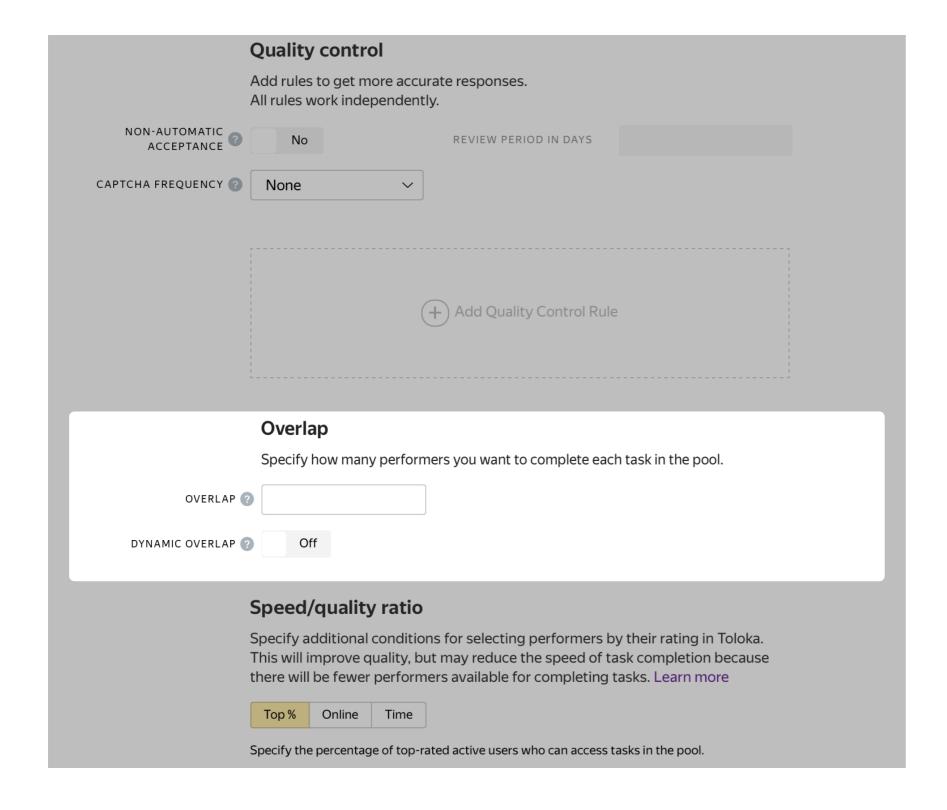
	MV	DS	GLAD	MMCE
Categories (K)				
Objects (J)				
Performers (W)	$\mathcal{N}^{1}$ $\mathcal{N}^{1}$	$\mathcal{N}^{1}$ $\mathcal{N}^{2}$ $\mathcal{N}^{3}$	$\mathcal{N}^{1}$ $\mathcal{N}^{2}$ $\mathcal{N}^{3}$	$\mathcal{N}^{1}$ $\mathcal{N}^{2}$ $\mathcal{N}^{3}$
Number of parameters	0	$WK^2 + K$	W + J	$(W + J)K^2$

#### Key components of labeling with crowds



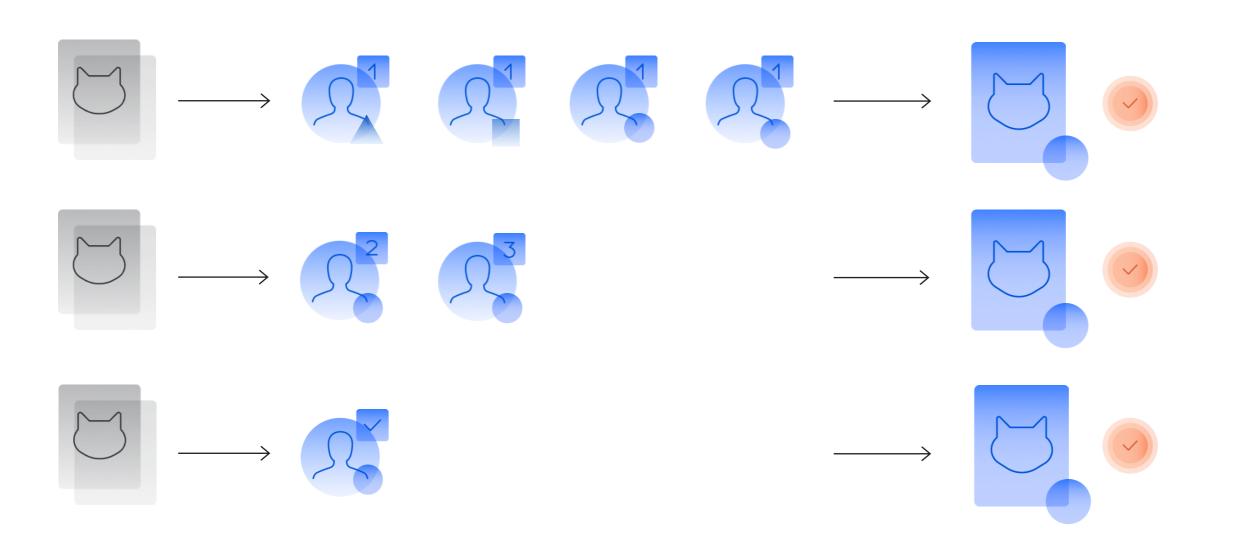
# Incremental relabeling aka dynamic overlap

#### Pool settings: dynamic overlap



#### Incremental relabeling problem

Obtain aggregated labels of a desired quality level using a fewer number of noisy labels



#### Incremental relabeling scheme (IRL)

Request a label for each object

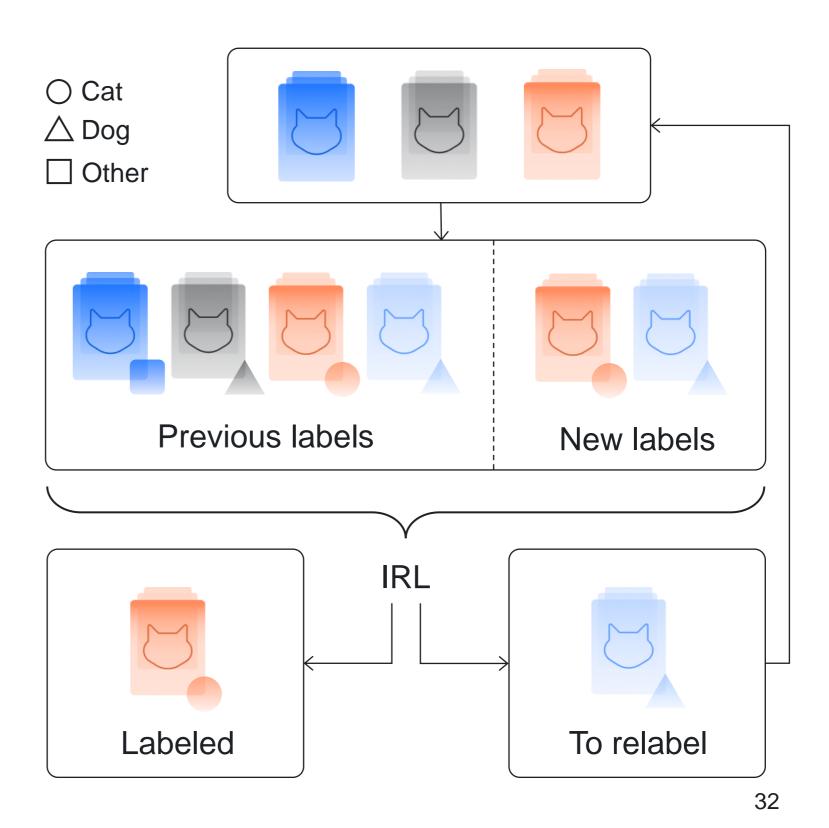
In real time IRL algorithm receives:

- (1) previously accumulated labels
- (2) new labels

#### Decides:

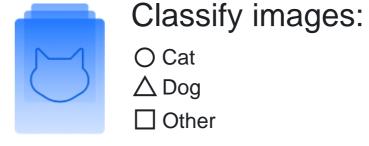
- (1) which objects are labeled
- (2) which objects to relabel

Repeat until all tasks are labeled

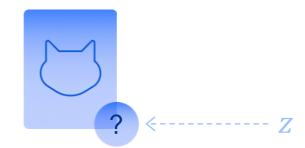


#### **Notations**

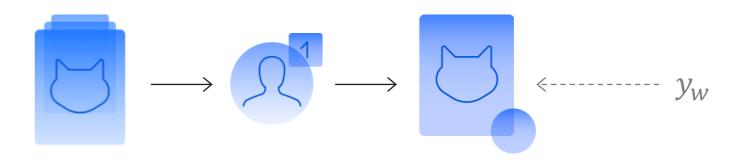
► Consider one object



 $ightharpoonup z \in \{1, ..., K\}$  — latent true label



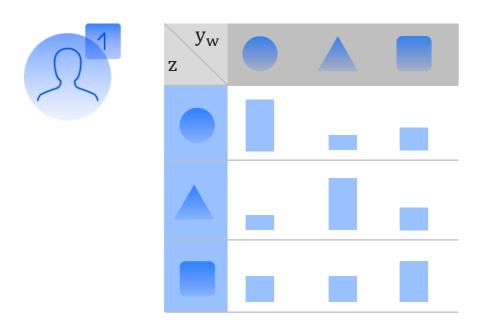
▶  $y_w \in \{1, ..., K\}$  — observed noisy label from performer w:



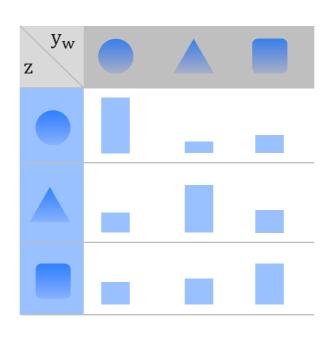
#### Notations

► Noisy label model for performer w:

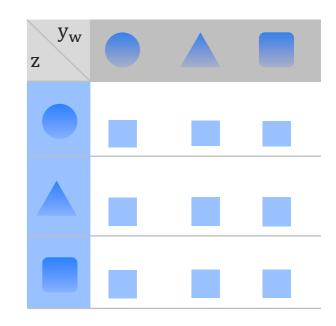
$$M_w \in [0,1]^{K \times K}$$
:  $Pr(Y_w = k | Z = c) = M_w[c, k]$ 











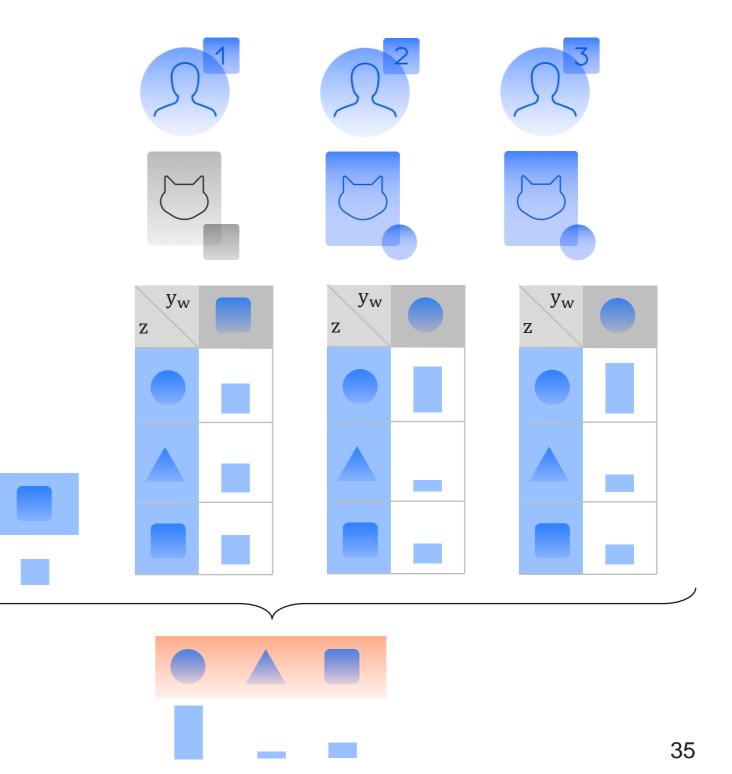
► Prior distribution:  $Pr(Z = k) = p_k$ 



#### Posterior distribution

- $\qquad \qquad \left\{ y_{w_1}, ..., y_{w_n} \right\} \text{accumulated noisy labels} \\ \text{for the object}$
- Using Bayes rule:

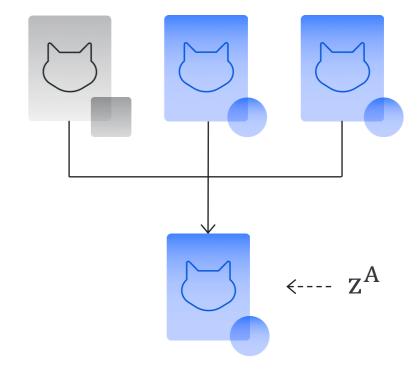
$$\begin{split} & \Pr(\mathbf{Z} = \mathbf{k} | \{y_{w_1}, ..., y_{w_n}\}) \\ &= \frac{\Pr(\mathbf{Z} = \mathbf{k}) \Pr(\{y_{w_1}, ..., y_{w_n}\} | \mathbf{Z} = \mathbf{k})}{\Pr(\{y_{w_1}, ..., y_{w_n}\})} \\ &= \frac{p_k \prod_{i=1}^n M_{w_i} [\mathbf{k}, y_{w_i}]}{\sum_{t=1}^K p_t \prod_{i=1}^n M_{w_i} [t, y_{w_i}]} \end{split}$$



#### Expected accuracy of aggregated labels

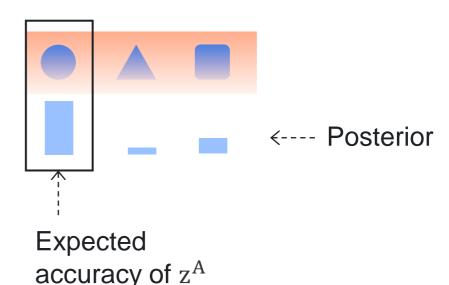
- ► Let A be an aggregation model, e.g. MV, DS, GLAD,...
- ▶ Denote aggregated label  $z^A = A(\{y_{w_1}, ..., y_{w_n}\})$
- Expected accuracy of aggregated labels given noisy labels is

$$E(\delta(z=z^A)|\{y_{w_1},...,y_{w_n}\}) = Pr(z=z^A|\{y_{w_1},...,y_{w_n}\})$$

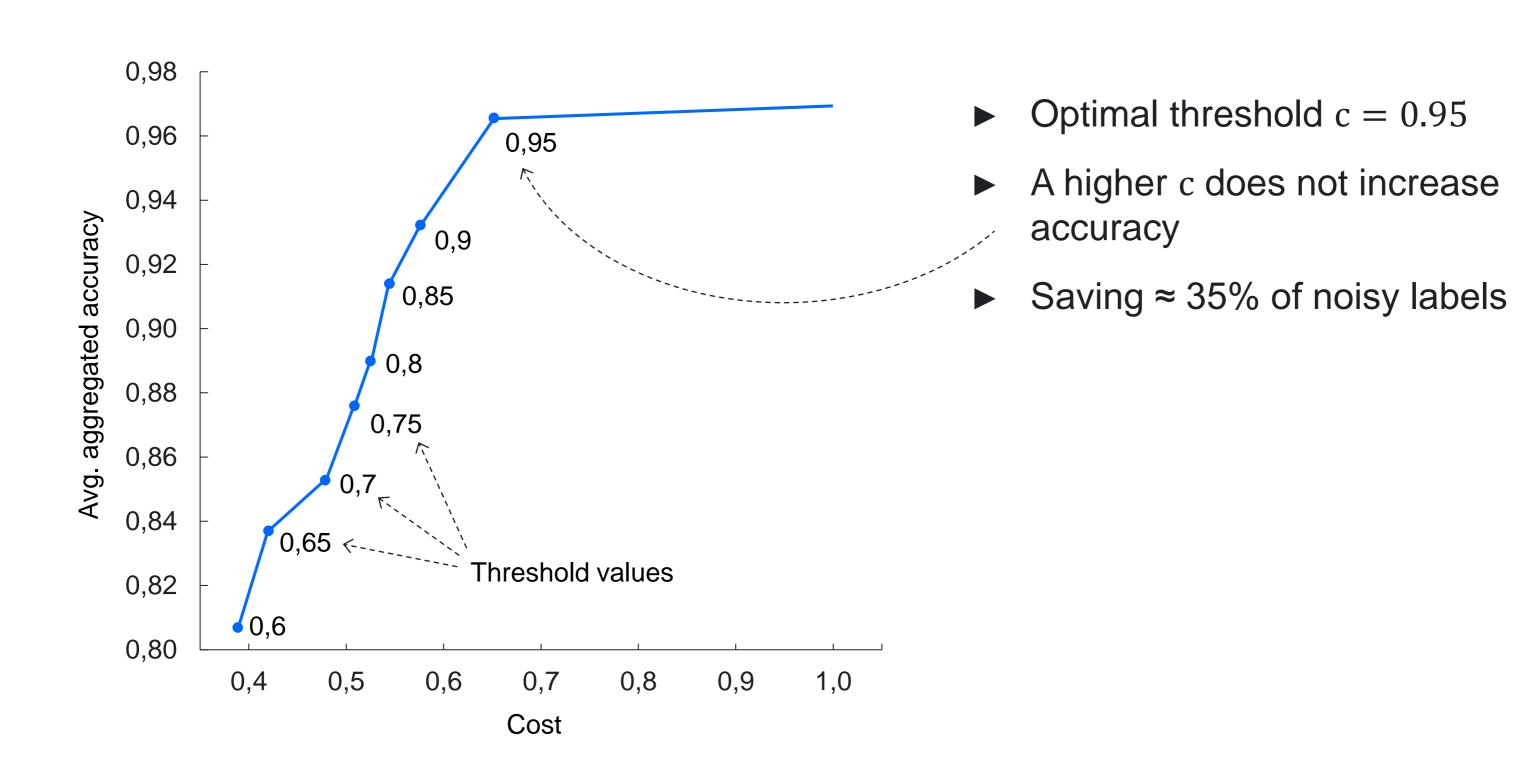


▶ Stop labeling if  $E(\delta(z = z^A) | \{y_{w_1}, ..., y_{w_n}\}) \ge C$ 

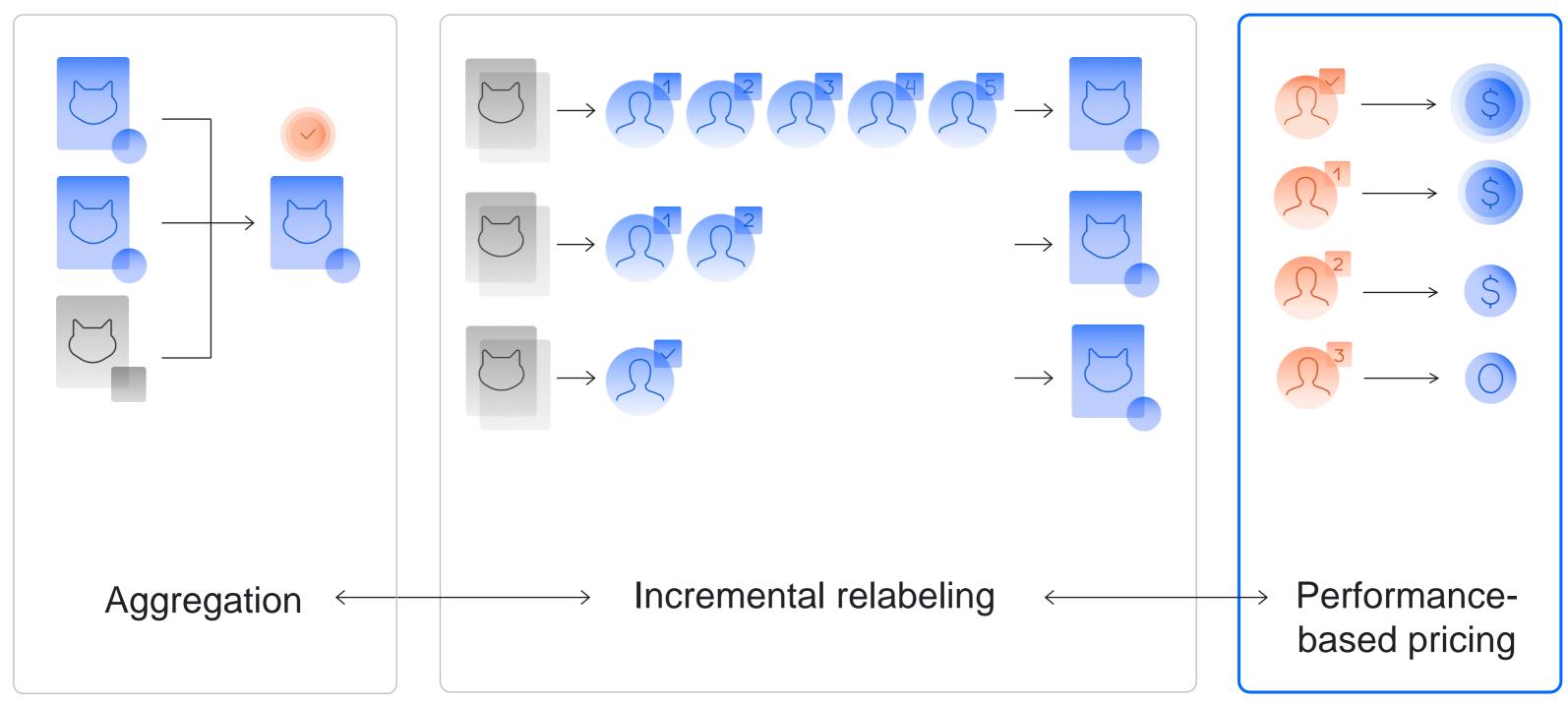
| | | Parameter



#### Threshold in IRL: cost – accuracy trade-off

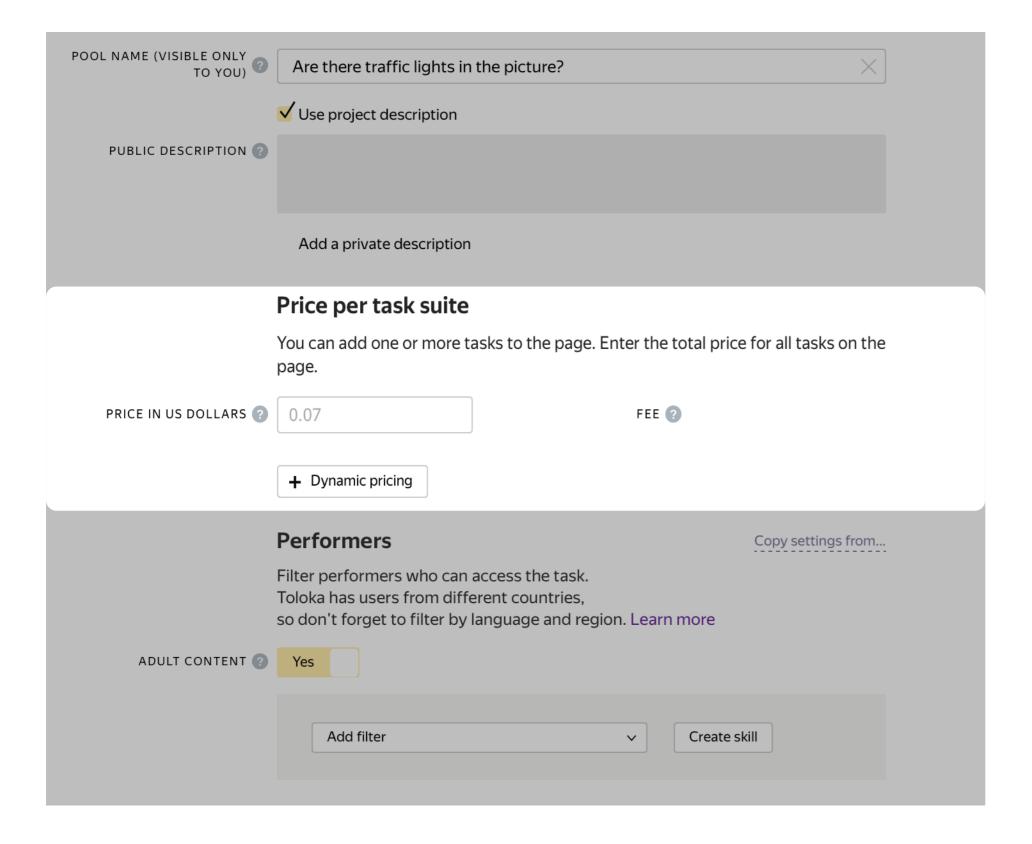


#### Key components of labeling with crowds

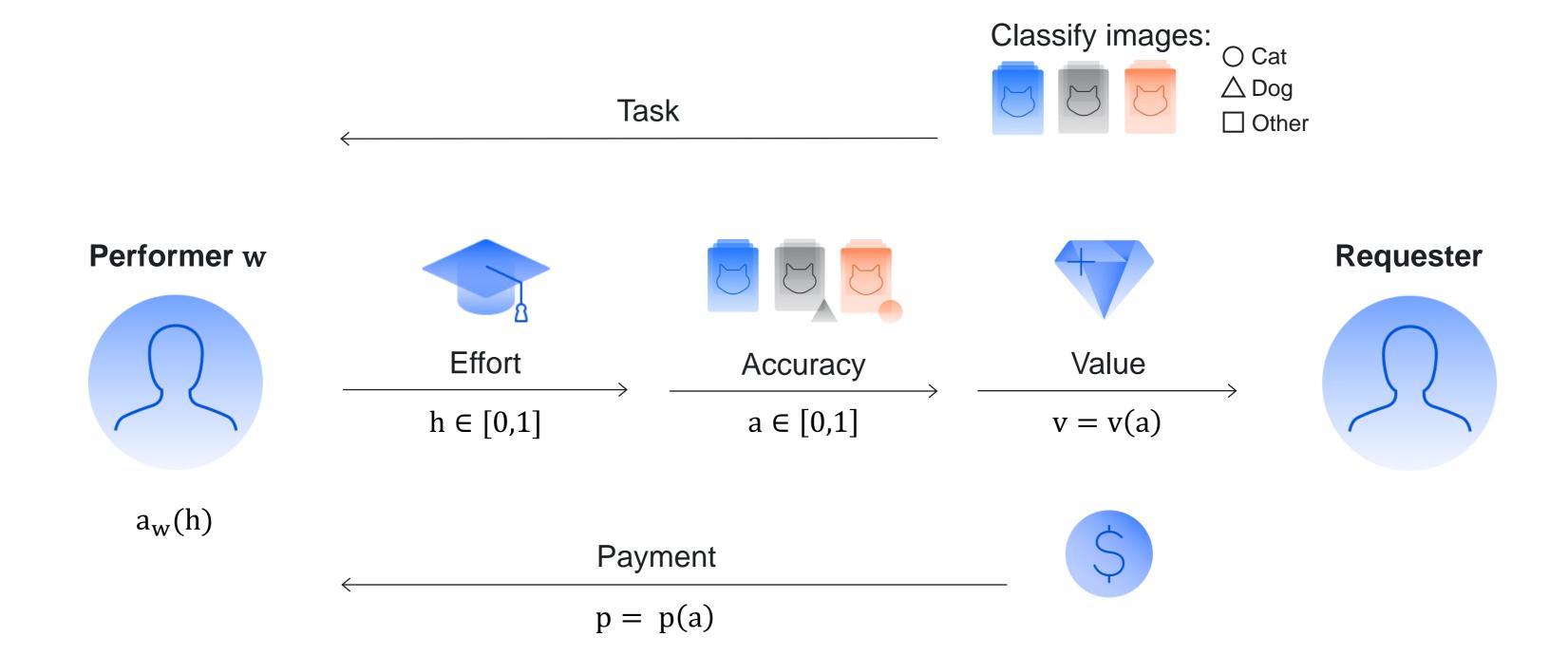


# Performance-based pricing aka dynamic pricing

#### Pool settings: dynamic pricing

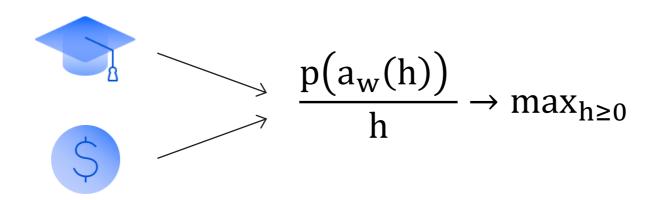


#### Labeling as a game: notation



#### Labeling as a game: formalization

► Each performer w chooses a level of effort h for labeling object to maximize earnings per unit of spent effort:



► The requester chooses a pricing p(a) to minimize payments per unit of obtained value

$$\frac{v(a)}{p(a)} \to \max_{a \in [0,1]}$$

# Labeling as a game: incentive compatible pricing

ightharpoonup Assume  $a_w(h)$  is a linear function of h:

$$a_w(h) = c_1h + c_0$$
Accuracy

The requester and the performers maximize their utility simultaneously if the pricing p(a) for each label is proportional to its accuracy a

#### Performance-based pricing in practice: settings

▶ Price p for the level of accuracy  $a_0$ :  $Pr(\hat{z} = z) \ge a_0$  E.g.:



 $\hat{q}_w = \Pr(y^w = z)$  — estimated quality level of performer w, e.g. the fraction of correct labels for golden set (GS):



5 correct GS among 10  $\hat{q}_w = 0.5$ 



16 correct GS among 20  $\hat{q}_w = 0.8$ 



100 correct GS among 100  $\hat{q}_w = 1$ 

#### Performance-based pricing in practice: settings

► Aggregation  $\hat{z}_j^{wMV} = \arg\max_{y=1,...,K} \sum_{w \in W_j} \hat{q}_w \delta(y = y_j^w)$ 



▶ IRL algorithm is based on the expected accuracy of  $\hat{z}_{j}^{wMV}$ 

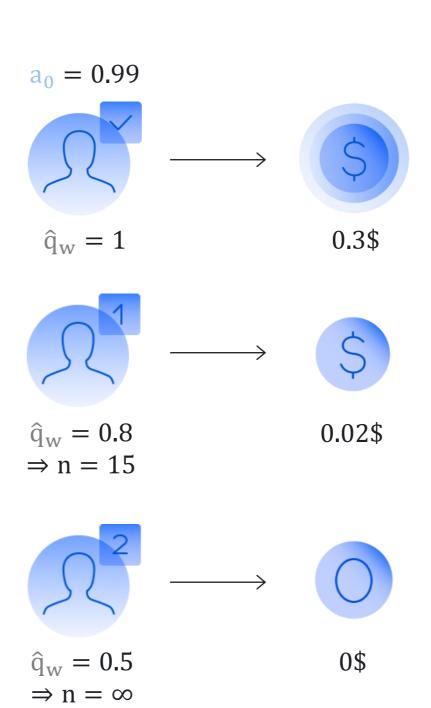
#### Performance-based pricing in practice

- Pricing rules
- 1. If  $\hat{q}_w \ge a_0$ , then the price is p
- 2. Else find n:

$$\sum_{k=0}^{n/2} {n \choose k} \hat{q}_{w}^{n-k} (1 - \hat{q}_{w})^{k} \ge a_{0}$$

Expected accuracy for MV

The price is p/n



#### Key components of labeling with crowds

